

### CSE 597: Security of Emerging Technologies Module: Program Analysis

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### Our Goal



## Do we need to implement control and data flow analysis from scratch?

- Most modern compilers already perform several types of such analysis for code optimization
  - ► We can hook into different layers of analysis and customize them
  - We still need to understand the details
- LLVM (http://llvm.org/) is a highly customizable and modular compiler framework
  - Users can write LLVM passes to perform different types of analysis
  - Clang static analyzer can find several types of bugs
  - ► Can instrument code for dynamic analysis

### **Compiler Overview**



- Abstract Syntax Tree : Source code parsed to produce AST
- Control Flow Graph: AST is transformed to CFG
- Data Flow Analysis: operates on CFG

### The Structure of a Compiler



### Syntactic Analysis

- Input: sequence of tokens from scanner
- **Output:** abstract syntax tree
- Actually,
  - ▶ parser first builds a <u>parse tree</u>, representation of grammars in a tree-like form.
  - ► AST is then built by translating the parse tree
  - ▶ parse tree rarely built explicitly; only determined by, say, how parser pushes stuff to stack

![](_page_6_Picture_0.jpeg)

- Source Code 4\*(2+3)
- Parser input

#### NUM(4) TIMES LPAR NUM(2) PLUS NUM(3) RPAR

• Parser output (AST):

![](_page_6_Figure_5.jpeg)

### Parse tree for the example: $4^{*}(2+3)$

![](_page_7_Figure_1.jpeg)

leaves are tokens

### Parse Tree

• Representation of grammars in a tree-like form.

A parse tree pictorially shows how the start symbol of a grammar derives a string in the language.... Dragon Book

• Is a one-to-one mapping from the grammar to a tree-form.

### Parse Tree

![](_page_9_Figure_1.jpeg)

### Abstract Syntax Tree (AST)

• Simplified syntactic representations of the source code, and they're most often expressed by the data structures of the language used for implementation

ASTs differ from parse trees because superficial distinctions of form, unimportant for translation, do not appear in syntax trees.... Dragon Book

• Without showing the whole syntactic clutter, represents the parsed string in a structured way, discarding all information that may be important for parsing the string, but isn't needed for analyzing it.

### Abstract Syntax Tree (AST)

#### C Statement: return a + 2

![](_page_11_Figure_2.jpeg)

### Disadvantages of ASTs

- AST has many similar forms
  - ► E.g., for, while, repeat...until
  - ► E.g., if, ?:, switch

int x = I // what's the value of x ?

// AST traversal can give the answer, right?

What about int x; x = I; or int x=0; x + = I; ?

- Expressions in AST may be complex, nested
   (x \* y) + (z > 5 ? 12 \* z : z + 20)
- Want simpler representation for analysis
  - ...at least, for dataflow analysis

### Control Flow Graph & Analysis

#### **High-level representation**

-Control flow is implicit in an AST

#### Low-level representation:

-Use a Control-flow graph (CFG)

- -Nodes represent statements (low-level linear IR)
- -Edges represent explicit flow of control

### What Is Control-Flow Analysis?

```
a := 0
1
        b := a * b
2
3
  L1: c := b/d
        if c < x goto L2
4
        e := b / c
5
        f := e + 1
6
7
  L2: g := f
        h := t - g
8
        if e > 0 goto L3
9
10 goto L1
11 L3: return
```

![](_page_14_Figure_2.jpeg)

### Basic Blocks

• A **basic block** is a sequence of straight line code that can be entered only at the beginning and exited only at the end

![](_page_15_Figure_2.jpeg)

#### Building basic blocks

- Identify leaders
  - The first instruction in a procedure, or
  - $\circ~$  The target of any branch, or
  - An instruction immediately following a branch (implicit target)
- Gobble all subsequent instructions until the next leader

### Basic Block Example

```
a := 0
1
        b := a * b
2
3
  L1: c := b/d
        if c < x goto L2
4
        e := b / c
5
        f := e + 1
6
7
  L2: g := f
        h := t - g
8
        if e > 0 goto L3
9
10 goto L1
11 L3: return
```

#### Leaders?

#### **Blocks**?

### Basic Block Example

```
a := 0
1
        b := a * b
2
3
  L1: c := b/d
        if c < x goto L2
4
      e := b / c
5
        f := e + 1
6
7
  L2: g := f
       h := t - g
8
       if e > 0 goto L3
9
10 goto L1
11 L3: return
```

Leaders? - {1, 3, 5, 7, 10, 11}

**Blocks?** 

 $-\{1,2\}$ 

 $-{3,4}$ 

- {5,6}

 $-\{10\}$ 

 $-\{11\}$ 

 $-\{7, 8, 9\}$ 

### Building a CFG From Basic Block

#### Construction

- Each CFG node represents a basic block
- There is an edge from node i to j if
  - Last statement of block i branches to the first statement of j, or
  - Block i does not end with an unconditional branch and is immediately followed in program order by block j (fall through)

![](_page_18_Figure_6.jpeg)

### Looping

![](_page_19_Figure_1.jpeg)

### Looping

![](_page_20_Figure_1.jpeg)

### Looping

![](_page_21_Picture_1.jpeg)

An entering block (or loop predecessor) is a non-loop node that has an edge into the loop (necessarily the header). If there is only one entering block entering block, and its only edge is to the header, it is also called the loop's preheader.

The **preheader** dominates the loop without itself being part of the loop.

- A latch is a loop node that has an edge to the header.
  - A **backedge** is an edge from a latch to the header.
  - An exiting edge is an edge from inside the loop to a node outside of the loop. The source of such an edge is called an exiting block, its target is an exit block.

### Dominators

- d dom i if all paths from entry to node i include d
- Strict Dominator (d sdom i)
  - If d dom i, but d !=i
- Immediate dominator (a idom b)
  - ► a sdom b and there does not exist any node c such that a != c, c != b, a dom c, c dom b
- Post dominator (p pdom i)
  - ► If every possible path from i to exit includes p

### Identifying Natural Loops and Dominators

- Back Edge
  - A **back edge** of a natural loop is one whose target dominates its source
- Natural Loop
  - ► The natural loop of a back edge (m→n), where n dominates m, is the set of nodes x such that n dominates x and there is a path from x to m not containing n

### Why go through all this trouble?

- Modern languages provide structured control flow
  - Shouldn't the compiler remember this information rather than throw it away and then re-compute it?

#### • Answers?

- ▶ We may want to work on the binary code
- Most modern languages still provide a goto statement
- Languages typically provide multiple types of loops. This analysis lets us treat them all uniformly
- We may want a compiler with multiple front ends for multiple languages; rather than translating each language to a CFG, translate each language to a canonical IR and then to a CFG

### Data flow analysis

- Derives information about the dynamic behavior of a program by only examining the static code
- Intraprocedural analysis
- Flow-sensitive: sensitive to the control flow in a function

# 1 a := 0 2 L1: b := a + 1 3 c := c + b 4 a := b \* 2 5 if a < 9 goto L1 6 return c</pre>

#### • Examples

- Live variable analysis
- Constant propagation
- Common subexpression elimination
- Dead code detection

- How many registers do we need?
- Easy bound: # of used variables (3)
- Need better answer

### Data flow analysis

![](_page_26_Figure_1.jpeg)

- Statically: finite program
- Dynamically: can have infinitely many paths
- Data flow analysis abstraction
  - For each point in the program, combines information of all instances of the same program point

### Liveness Analysis

#### Definition

- A variable is **live** at a particular point in the program if its value at that point will be used in the future (**dead**, otherwise).
  - To compute liveness at a given point, we need to look into the future

#### **Motivation: Register Allocation**

- A program contains an unbounded number of variables
- Must execute on a machine with a bounded number of registers
- Two variables can use the same register if they are never in use at the same time (i.e, never simultaneously live).
  - -Register allocation uses liveness information

### Control Flow Graph

- Let's consider CFG where nodes contain program statement instead of basic block.
- Example
  - I. a := 0
  - 2. LI:b := a + I
  - 3. c:= c + b
  - 4. a := b \* 2
  - 5. if a < 9 goto LI
  - 6. return c

![](_page_28_Figure_9.jpeg)

### Liveness by Example

- Live range of b
  - Variable b is read in line 4, so b is live on 3->4 edge
  - b is also read in line 3, so b is live on (2->3) edge
  - Line 2 assigns b, so value of b on edges (1->2) and (5->2) are not needed. So b is dead along those edges.
- b's live range is (2->3->4)

![](_page_29_Figure_6.jpeg)

### Liveness by Example

- Live range of a
  - (I->2) and (4->5->2)
  - a is dead on (2->3->4)

![](_page_30_Figure_4.jpeg)

### Terminology

- Flow graph terms
  - A CFG node has out-edges that lead to successor nodes and in-edges that come from **predecessor** nodes
  - pred[n] is the set of all predecessors of node n
  - succ[n] is the set of all successors of node n

#### **Examples**

- Out-edges of node 5:  $(5\rightarrow 6)$  and  $(5\rightarrow 2)$
- succ[5] = {2,6}
- $\text{pred}[5] = \{4\}$  $\text{pred}[2] = \{1,5\}$

![](_page_31_Figure_9.jpeg)

![](_page_31_Figure_10.jpeg)

### Uses and Defs

#### Def (or definition)

-An **assignment** of a value to a variable

-def[v] = set of CFG nodes that define variable v

-def[n] = set of variables that are defined at node n

#### Use

-A read of a variable's value
-use[v] = set of CFG nodes that use variable v
-use[n] = set of variables that are used at node n

#### More precise definition of liveness

- A variable v is live on a CFG edge if
  - (1)∃ a directed path from that edge to a use of v(node in use[v]), and
  - (2)that path does not go through any def of v (no nodes in def[v])

![](_page_32_Figure_11.jpeg)

![](_page_32_Figure_12.jpeg)

![](_page_32_Figure_13.jpeg)

### The Flow of Liveness

- Data-flow
  - Liveness of variables is a property that flows through the edges of the CFG
- Direction of Flow
  - Liveness flows backwards through the CFG, because the behavior at future nodes determines liveness at a given node

![](_page_33_Figure_5.jpeg)

### Liveness at Nodes

![](_page_34_Figure_1.jpeg)

#### **Two More Definitions**

- A variable is live-out at a node if it is live on any out edges
- A variable is live-in at a node if it is live on any in edges

![](_page_34_Figure_5.jpeg)

### **Computing Liveness**

- Generate liveness: If a variable is in use[n], it is live-in at node n
- Push liveness across edges:
  - If a variable is live-in at a node n
  - then it is live-out at all nodes in pred[n]
- Push liveness across nodes:
  - ▶ If a variable is live-out at node n and not in def[n]
  - ▶ then the variable is also live-in at n
- Data flow Equation:  $in[n] = use[n] \cup (out[n] def[n])$

```
out[n] = \bigcup in[s]
s \in succ[n]
```

### Solving Dataflow Equation

```
for each node n in CFG
               in[n] = \emptyset; out[n] = \emptyset
                                                         Initialize solutions
repeat
          for each node n in CFG
                                                        Save current results
                   in'[n] = in[n]
                   out'[n] = out[n]
                    in[n] = use[n] \cup (out[n] - def[n])
                                                                  Solve data-flow equation
                    out[n] = \cup in[s]
                             s \in succ[n]
                                                             Test for convergence
until in'[n]=in[n] and out'[n]=out[n] for all n
```

### Computing Liveness Example

			1	st	2	nd	3	rd	4t	h	5t	h	61	h	7t	h
node #	use	def	in	out												
1		a				a		a		ac	с	ac	с	ac	с	ac
2	а	b	a		a	bc	ac	bc								
3	bc	с	bc		bc	b	bc	b	bc	b	bc	b	bc	bc	bc	bc
4	b	a	b		b	a	b	a	b	ac	bc	ac	bc	ac	bc	ac
5	a		a	a	a	ac	ac	ac								
6	с		с		с		с		с		с		с		с	
		I														

![](_page_37_Figure_2.jpeg)

### Iterating Backwards: Converges Faster

			18	st	21	nd	31	d
node #	use	def	out	in	out	in	out	in
6	с			с		с		с
5	а		с	ac	ac	ac	ac	ac
4	b	a	ac	bc	ac	bc	ac	bc
3	bc	с	bc	bc	bc	bc	bc	bc
2	а	b	bc	ac	bc	ac	bc	ac
1		a	ac	с	ac	с	ac	с

![](_page_38_Figure_2.jpeg)

### Liveness Example: Round I

A variable is **live** at a particular point in the program if its value at that point will be used in the future (**dead**, otherwise).

#### Algorithm

![](_page_39_Figure_3.jpeg)

I. a = 0

Nod

e

6

def

use

С

![](_page_40_Figure_0.jpeg)

![](_page_41_Figure_0.jpeg)

### Conservative Approximation

				X	Y		1	Z
node #	use	def	in	out	in	out	in	out
1		a	с	ac	co	l acd	с	ac
2	а	b	ac	bc	acc	l bcd	ac	b
3	bc	с	bc	bc	bco	l bcd	b	b
4	b	a	bc	ac	bco	l acd	b	ac
5	а		ac	ac	acd	acd	ac	ac
6	с		с		с		с	

#### Solution X:

- From the previous slide

![](_page_42_Figure_4.jpeg)

### Conservative Approximation

				X		Y	1	Z
node #	use	def	in	out	in	out	in	out
1		a	с	ac	cd	l acd	с	ac
2	а	b	ac	bc	acd	bcd	ac	b
3	bc	с	bc	bc	bcd	l bcd	b	b
4	b	a	bc	ac	bcd	lacd	b	ac
5	а		ac	ac	acd	acd	ac	ac
6	с		с		с		с	

#### Solution Y:

Carries variable d uselessly

- DoesY lead to a correct program?

![](_page_43_Figure_5.jpeg)

Imprecise conservative solutions  $\Rightarrow$  sub-optimal but correct programs

### **Conservative Approximation**

			2	X		Y		Z
node #	use	def	in	out	in	out	in	out
1		a	с	ac	cd	l acd	с	ac
2	а	b	ac	bc	acd	bcd	ac	b
3	bc	с	bc	bc	bcd	l bcd	b	b
4	b	a	bc	ac	bcd	l acd	b	ac
5	а		ac	ac	acd	acd	ac	ac
6	с		с		с		с	

#### Solution Z:

Does not identify c as live in all cases – Does Z lead to a correct program?

![](_page_44_Figure_4.jpeg)

**Non-conservative solutions**  $\Rightarrow$  **incorrect programs** 

### Need for approximation

 Static vs. Dynamic Liveness: b\*b is always non-negative, so c >= b is always true and a's value will never be used after node

![](_page_45_Figure_2.jpeg)

No compiler can statically identify all infeasible paths

### Liveness Analysis Example Summary

- Live range of a
  - (I->2) and (4->5->2)
- Live range of b
  - (2->3->4)
- Live range of c
  - Entry->1->2->3->4->5->2, 5->6

You need 2 registers Why?

![](_page_46_Figure_8.jpeg)

### Example 2: Reaching Definition

#### Definition

 A definition (statement) d of a variable v reaches node n if there is a path from d to n such that v is not redefined along that path

#### Uses of reaching definitions

- Build use/def chains
- Constant propagation
- Loop invariant code motion

![](_page_47_Figure_7.jpeg)

![](_page_47_Figure_8.jpeg)

#### Reaching definitions of a and b

To determine whether it's legal to move statement 4 out of the loop, we need to ensure that there are no reaching definitions of **a** or **b** inside the loop

### Computing Reaching Definition

- Assumption: At most one definition per node
- Gen[n]: Definitions that are generated by node n (at most one)
- Kill[n]: Definitions that are killed by node n

<u>statement</u>	<u>gen's</u>	<u>kills</u>
x:=y	{y}	{x}
x:=p(y,z)	{y,z}	{x}
x:=*(y+i)	{y,i}	{x}
*(v+i):=x	{x}	{}
$x := f(y_1,, y_n)$	$\{f, y_1, \dots, y_n\}$	{x}

### Data-flow equations for Reaching Definition

#### The in set

 A definition reaches the beginning of a node if it reaches the end of any of the predecessors of that node

![](_page_49_Figure_3.jpeg)

#### The out set

 A definition reaches the end of a node if (1) the node itself generates the definition or if (2) the definition reaches the beginning of the node and the node does not kill it

### **Recall Liveness Analysis**

• Data-flow Equation for liveness

 $in[n] = use[n] \cup (out[n] - def[n])$ • Liver  $out[n] = \bigcup_{s \in succ[n]} in[s]$ s of Gen and Kill

$$in[n] = gen[n] \cup (out[n] - kill[n])$$
  

$$out[n] = \bigcup_{s \in succ[n]} in[s]$$
  
A use of a variable generates liveness  
A def of a variable kills liveness

**Gen:** New information that's added at a node **Kill:** Old information that's removed at a node

Can define almost any data-flow analysis in terms of Gen and Kill

### **Direction of Flow**

#### **Backward data-flow analysis**

 Information at a node is based on what happens later in the flow graph i.e., in[] is defined in terms of out[]

$$in[n] = gen[n] \qquad \bigcup \quad (out[n] - kill[n])$$
$$out[n] = \bigcup_{s \in succ[n]} in[s]$$

![](_page_51_Figure_4.jpeg)

#### Forward data-flow analysis

Information at a node is based on what happens earlier in the flow graph *i.e.*, out[] is defined in terms of in[]

$$in[n] = \bigcup_{\substack{p \in pred[n] \\ out[n] = gen[n]}} out[p]$$
$$\bigcup (in[n] - kill[n])$$

#### Some problems need both forward and backward analysis

- e.g., Partial redundancy elimination (uncommon)

### Data-Flow Equation for reaching definition

#### Symmetry between reaching definitions and liveness

- Swap in[] and out[] and swap the directions of the arcs

**Reaching Definitions** 

$$in[n] = \bigcup_{p \in pred[n]} out[s]$$
  
out[n] = gen[n]  $\bigcup$  (in[n] - kill[n]

#### Live Variables

$$out[n] = \bigcup_{s \in succ[n]} in[s]$$
$$in[n] = gen[n] \cup (out[n] - kill[n])$$

![](_page_52_Figure_7.jpeg)

### Available Expression

• An expression, **x+y**, is **available** at node n if every path from the entry node to n evaluates **x+y**, and there are no definitions of **x** or **y** after the last evaluation.

![](_page_53_Figure_2.jpeg)

### Available Expression for CSE

#### Common Subexpression eliminated

▶ If an expression is available at a point where it is evaluated, it need not be recomputed

![](_page_54_Figure_3.jpeg)

### Must vs. May analysis

- May information: Identifies possibilities
- Must information: Implies a guarantee

	May	Must
Forward	Reaching Definition	Available Expression
Backward	Live Variables	Very Busy Expression

![](_page_56_Picture_0.jpeg)

![](_page_56_Picture_1.jpeg)

### Thanks to Suman Jana and Baishakhi Ray for some slides.